



SIGNAL  
ANALYSIS &  
IMAGING GROUP

# **A comparative study of seismic reconstruction for arbitrary irregular-grid acquisition: I-FMSSA vs. EPOCS**

Rongzhi Lin

[rongzhi@ualberta.ca](mailto:rongzhi@ualberta.ca)

## 1. Introduction

## 2. Method

- Extended POCS (EPOCS)
- Interpolated-FMSSA (I-FMSSA)
- Fast and computational MSSA (FMSSA)

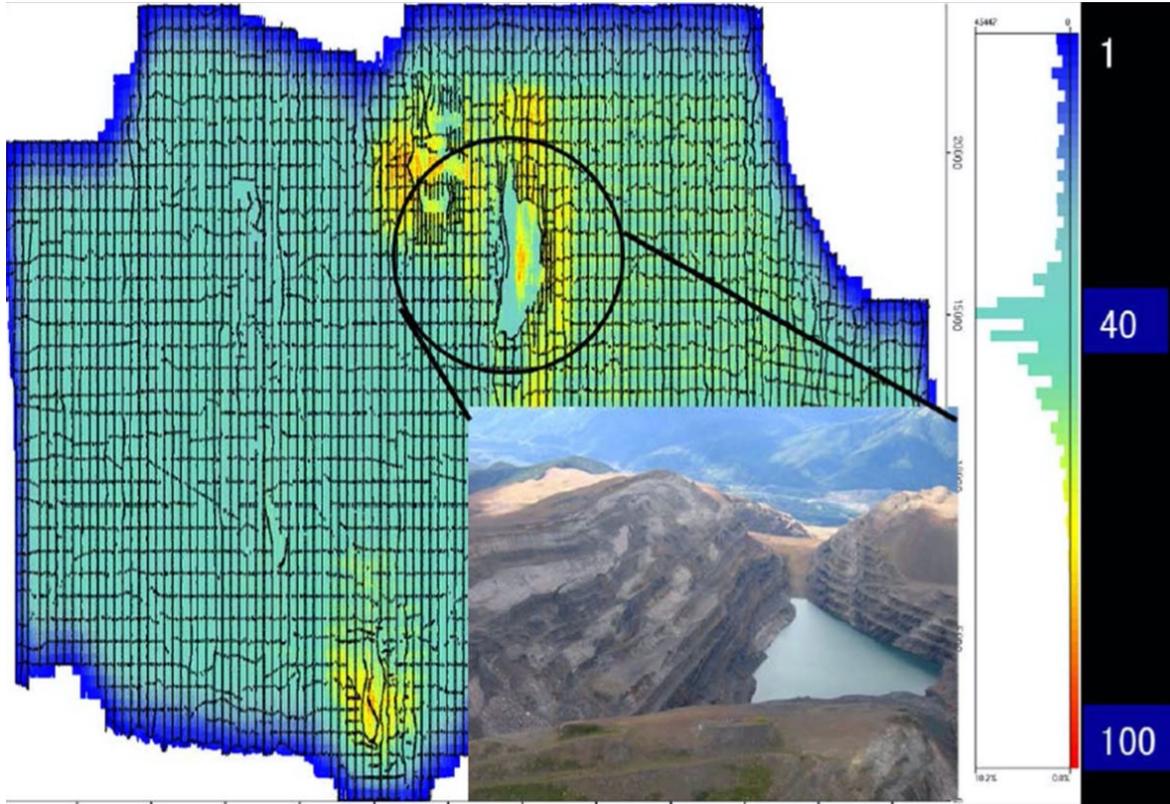
## 3. Synthetic example

- Without random noise
- With random noise

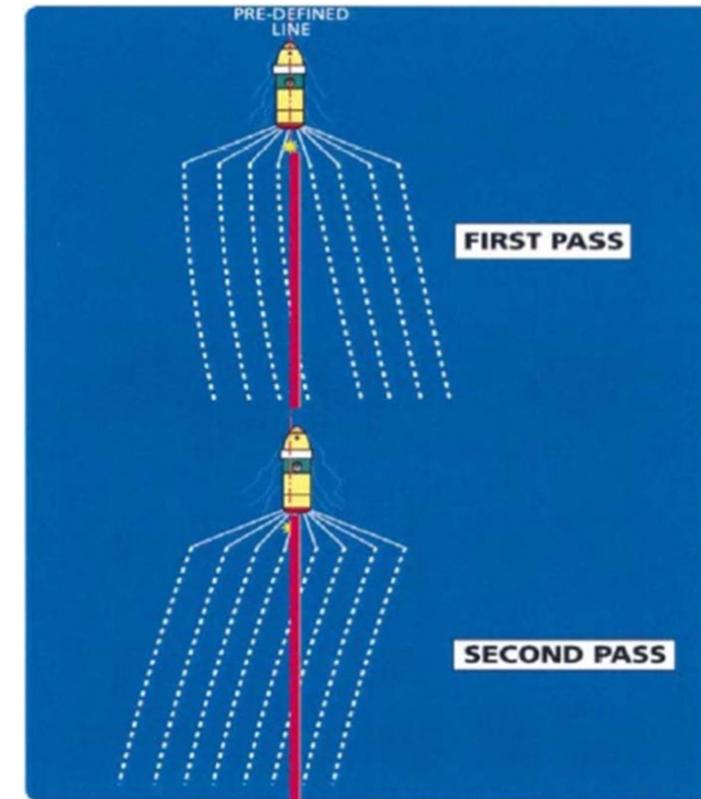
## 4. Real data example

## 5. Conclusion

## 6. Acknowledgement



(a) Irregularity caused by obstacles (Trad,2008).

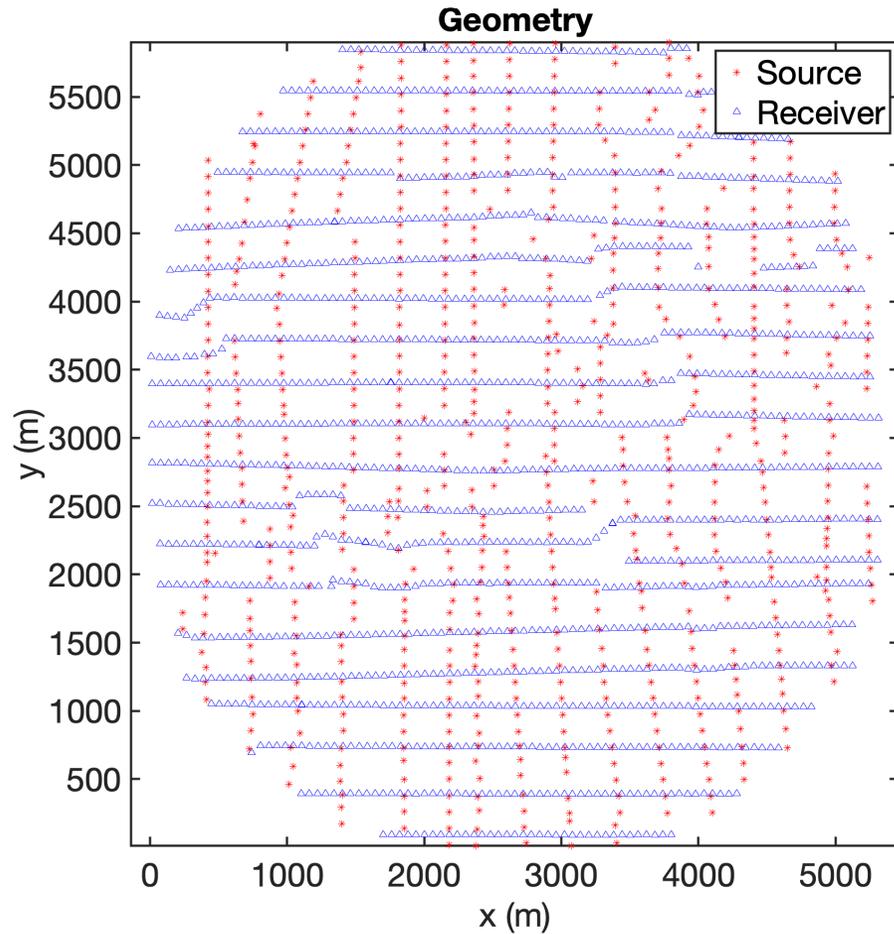


(b) Irregularity caused by feathering (Eiken et al.,2003).

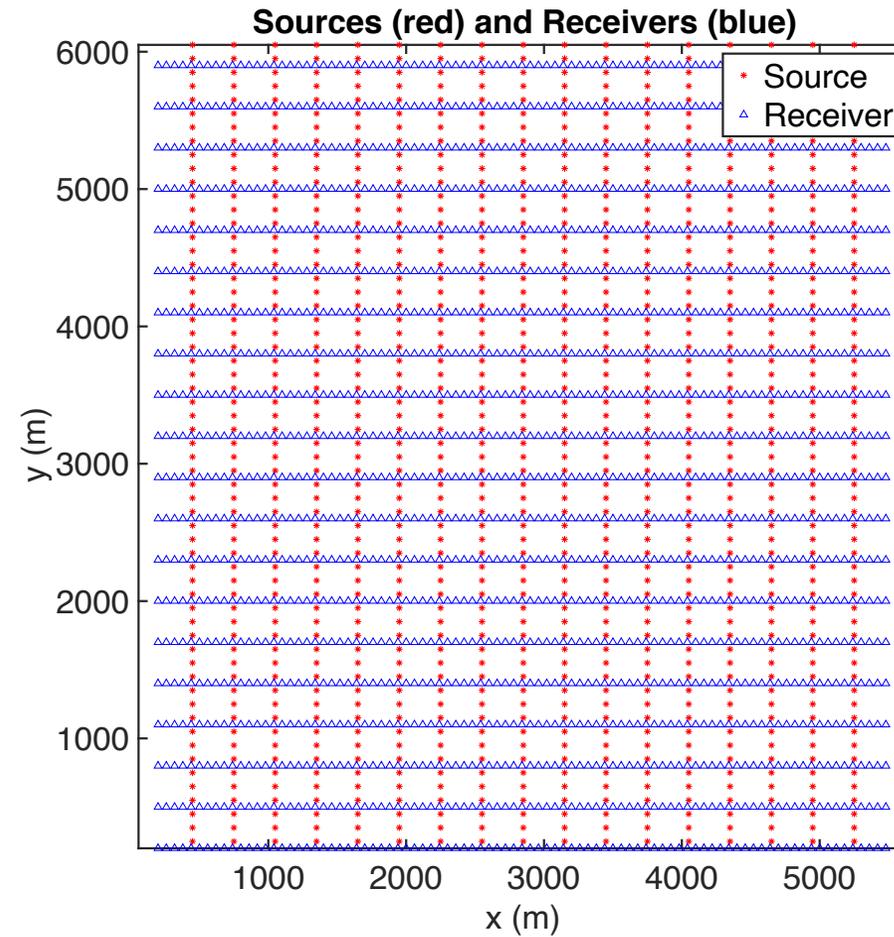
Many factors, such as **obstacles** and **featherings**, will lead to irregular distributions of seismic sources and receivers.

## 1. Natural observed irregularity

Observed irregular grid

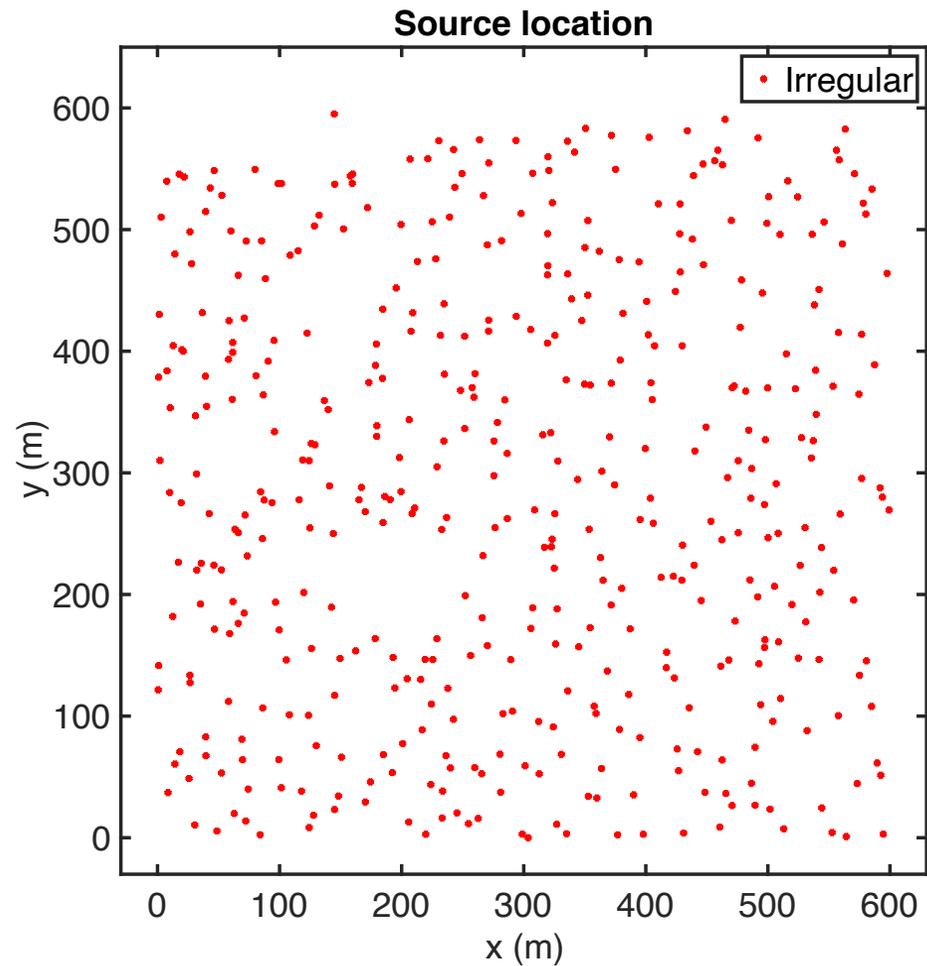


Desired regular grid

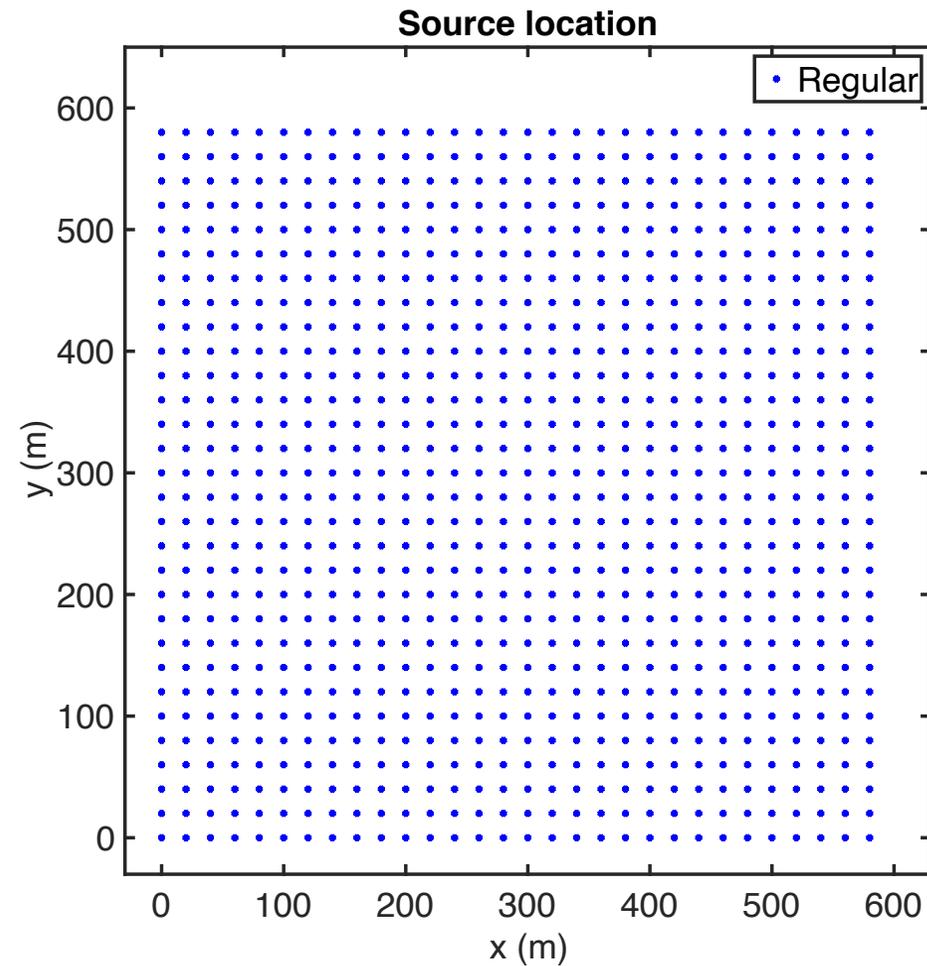


## 2. Human-made irregularity

### CS-based irregular grid



### Desired regular grid



# Methods (EPOCS vs. I-FMSSA)

---



- ***POCS***

(Abma and Kabir, 2006)

$$\mathbf{d}_{k+1} = \mathbf{d}_{obs} + (\mathbf{I} - \mathcal{R}) \mathcal{S}^T \mathbf{T}_k (\mathcal{S} \mathbf{d}_k)$$

*Sampling operator*

$$\mathcal{R}_{ij} = \begin{cases} 1 & \text{if one trace is assigned to grid point } (i, j) \\ 0 & \text{if grid point } (i, j) \text{ is empty} \end{cases}$$

- $\mathcal{S}$  is a promoting transform
- $\mathbf{T}_k$  is the iterative hard thresholding operator

- ***EPOCS***

(Jiang et al., 2017)

$$\mathbf{d}_{k+1} = \mathcal{W}^* \hat{\mathbf{d}}_{obs} + (\mathbf{I} - \mathcal{W}^* \mathcal{W}) \mathcal{S}^T \mathbf{T}_k (\mathcal{S} \mathbf{d}_k)$$

*Interpolation operator*

$$\begin{aligned} \mathcal{W}^* &: \text{irregular} \rightarrow \text{regular} \\ \mathcal{W} &: \text{regular} \rightarrow \text{irregular} \end{aligned}$$

- *Sinc-Kaiser interpolator*

- ***I-FMSSA*** (with low rank constraint) ( Carozzi and Sacchi, 2021)

$$J = \|\mathbf{d}_{obs} - \mathcal{W}\mathbf{d}\|_2^2 \quad s.t. \quad rank(\mathbf{d}) \leq k$$

$$\mathbf{d}_{k+1} = \mathcal{P}[\mathbf{d}_k - \lambda \mathcal{W}^*(\mathcal{W}\mathbf{d}_k - \mathbf{d}_{obs})]$$

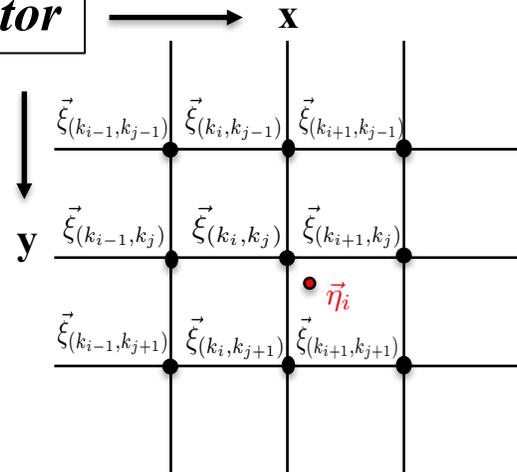
$\mathcal{W}^*$  : irregular  $\rightarrow$  regular

$\mathcal{W}$  : regular  $\rightarrow$  irregular

Projection operator = FMSSA (or MSSA)

- ***I-FMSSA***: Projection operator = FMSSA
- ***I-MSSA***: Projection operator = MSSA

- ***Interpolation operator***



Kaiser windowed *sinc* interpolation with  $N=1$

$$\mathcal{W}_k(t) = \text{sinc}(\pi t) \frac{I_0\left(a\sqrt{1 - (t/(N+1))^2}\right)}{I_0(a)}$$

- *MSSA*

- Step 1:  $d(x, t) \xrightarrow{\mathcal{F}(t)} D(f, t).$
- Step 2: *Build Hankel matrix*
- Step 3: *Rank-reduction (SVD)*
- Step 4: *Anti-diagonal averaging*
- Step 5:  $\hat{d}(x, t) \xleftarrow{\mathcal{F}^{-1}(t)} \hat{D}(f, t).$

- *FMSSA*

(Cheng et al. 2019)

*Avoid Hankel structured matrices*

- Hankel matrix vector products are computed via **FFT**

*To speed up rank reduction*

- **RQRd** is adopted to replace SVD.

*To improve anti-diagonal averaging*

- Eigenimages are computed via **convolutions**.

▪ Step 2: *Build Hankel matrix*



*Avoid Hankel structured matrices*

- Hankel matrix vector products are computed via **FFT**

• Fast Hankel matrix vector product

➤ Hankel matrices can be embedded into circulant matrices

$$\mathbf{C} = \begin{bmatrix} D_2 & D_1 & D_3 \\ D_3 & D_2 & D_1 \\ D_1 & D_3 & D_2 \end{bmatrix} = \begin{bmatrix} D_3 & D_1 & D_2 \\ D_1 & D_2 & D_3 \\ D_2 & D_3 & D_1 \end{bmatrix} \begin{bmatrix} & & 1 \\ & 1 & \\ 1 & & \end{bmatrix}$$

➤ A Circulant matrix  $\mathbf{C}$  multiplies a vector  $\mathbf{x}$  are computed via FFT

$$\mathbf{H}\mathbf{x} = \begin{bmatrix} D_1 & D_2 \\ D_2 & D_3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} D_2 & D_1 & D_3 \\ D_3 & D_2 & D_1 \\ D_1 & D_3 & D_2 \end{bmatrix} \begin{bmatrix} x_2 \\ x_1 \\ 0 \end{bmatrix} = \mathbf{C}\hat{\mathbf{x}} = \mathcal{F}^{-1}(\mathcal{F}(\mathbf{c}) \circ \mathcal{F}(\hat{\mathbf{x}}))$$

(Cheng et al. 2019)

where  $\mathbf{c} = [D_2 \ D_3 \ D_1]^T$  and  $\hat{\mathbf{x}} = [x_2 \ x_1 \ 0]^T$

- Step 3: *Rank-reduction (SVD)*  $\longrightarrow$  *To speed up rank reduction*
  - **RQRd** is adopted to replace SVD.

- Randomized QR decomposition (RQRd)

1. Projection onto random sets:

$$\begin{array}{ccc}
 X & = & H \quad \Omega \\
 M \times p & & M \times L \quad L \times p
 \end{array}$$

$\Omega$  are  $p$  random vectors, and  $p \ll L$

2. Economic-size QR decomposition:

$$\begin{array}{ccc}
 Q & R & = \quad qr(X) \\
 M \times p & p \times p & \quad M \times p
 \end{array}$$

3. Low-rank approximation:

$$\hat{H} = QQ^H H$$

*(Cheng et al. 2019)*

- Step 4: *Anti-diagonal averaging*  $\longrightarrow$  *Fast anti-diagonal averaging*
  - Eigenimages are computed via **convolutions**.

- Fast anti-diagonal averaging

For one linear event (rank=1 case)

- Let  $p = 1$ :  $\hat{\mathbf{H}} = \mathbf{q}_1 \mathbf{q}_1^H \mathbf{H}$

$$\text{Let } \mathbf{t}_1 = \mathbf{q}_1^H \mathbf{H}, \text{ we get } \hat{\mathbf{H}} = \mathbf{q}_1 \mathbf{t}_1$$

- For **anti-diagonal averaging**:

$$\hat{\mathbf{D}} = \begin{cases} \frac{1}{i} \sum_{j=1}^i q_{1j} t_{1-j+1}, & 1 \leq i \leq M \\ \frac{1}{M} \sum_{j=1}^M q_{1j} t_{1-i-j+1}, & M \leq i \leq L \\ \frac{1}{N-i+1} \sum_{j=i-L+1}^M q_{1j} t_{1-i-j+1}, & L \leq i \leq N \end{cases} = w \sum_{j=1}^N q_{1j} t_{1-i-j+1} \xleftarrow{\text{Convolution}}$$

- For rank =  $p$

$$\hat{\mathbf{D}} = w \circ [(\mathbf{q}_1 * \mathbf{t}_1) + (\mathbf{q}_2 * \mathbf{t}_2) + \cdots + (\mathbf{q}_p * \mathbf{t}_p)]$$

(Cheng et al. 2019)

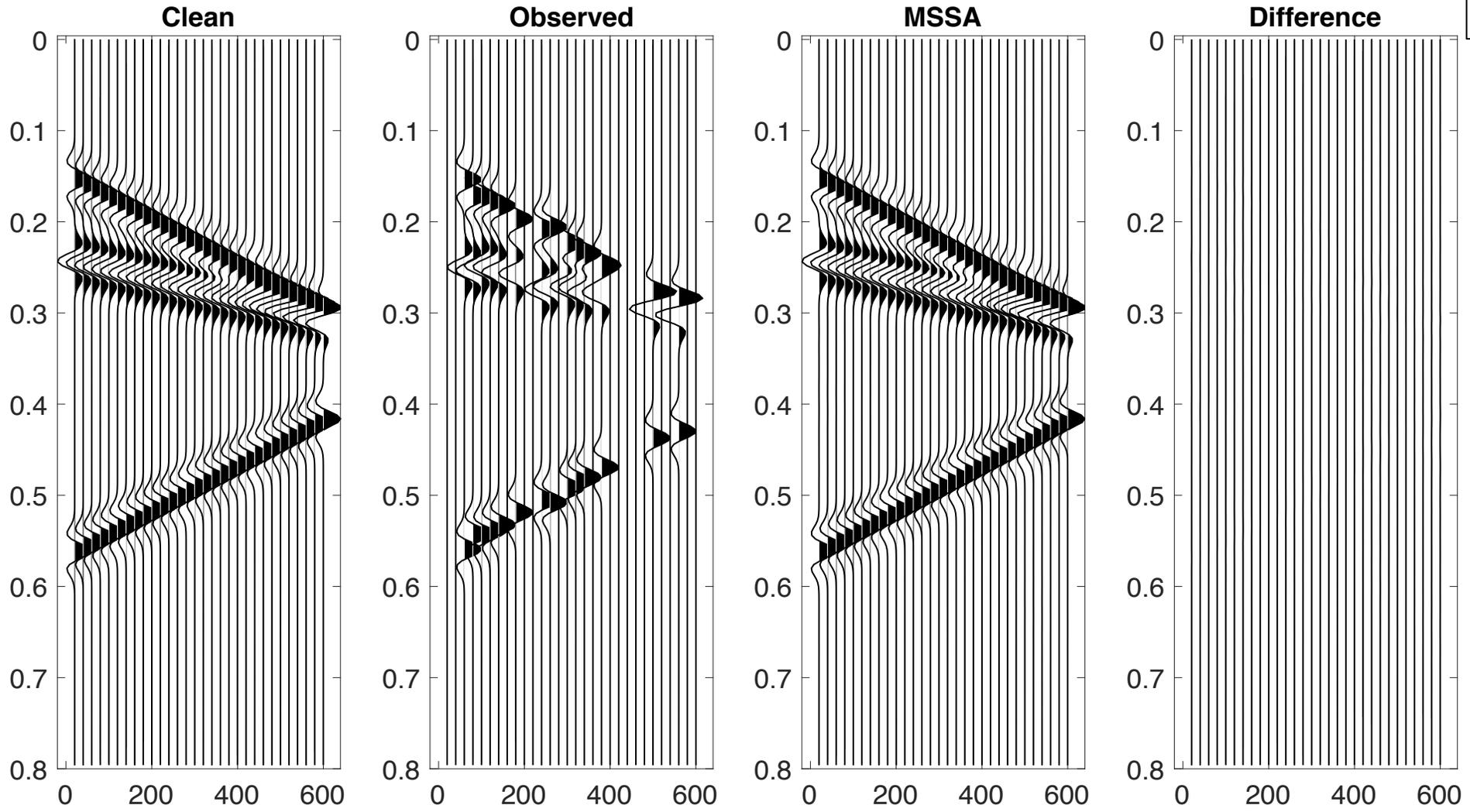
# I-MSSA vs. I-FMSSA (Computational efficiency?)

---



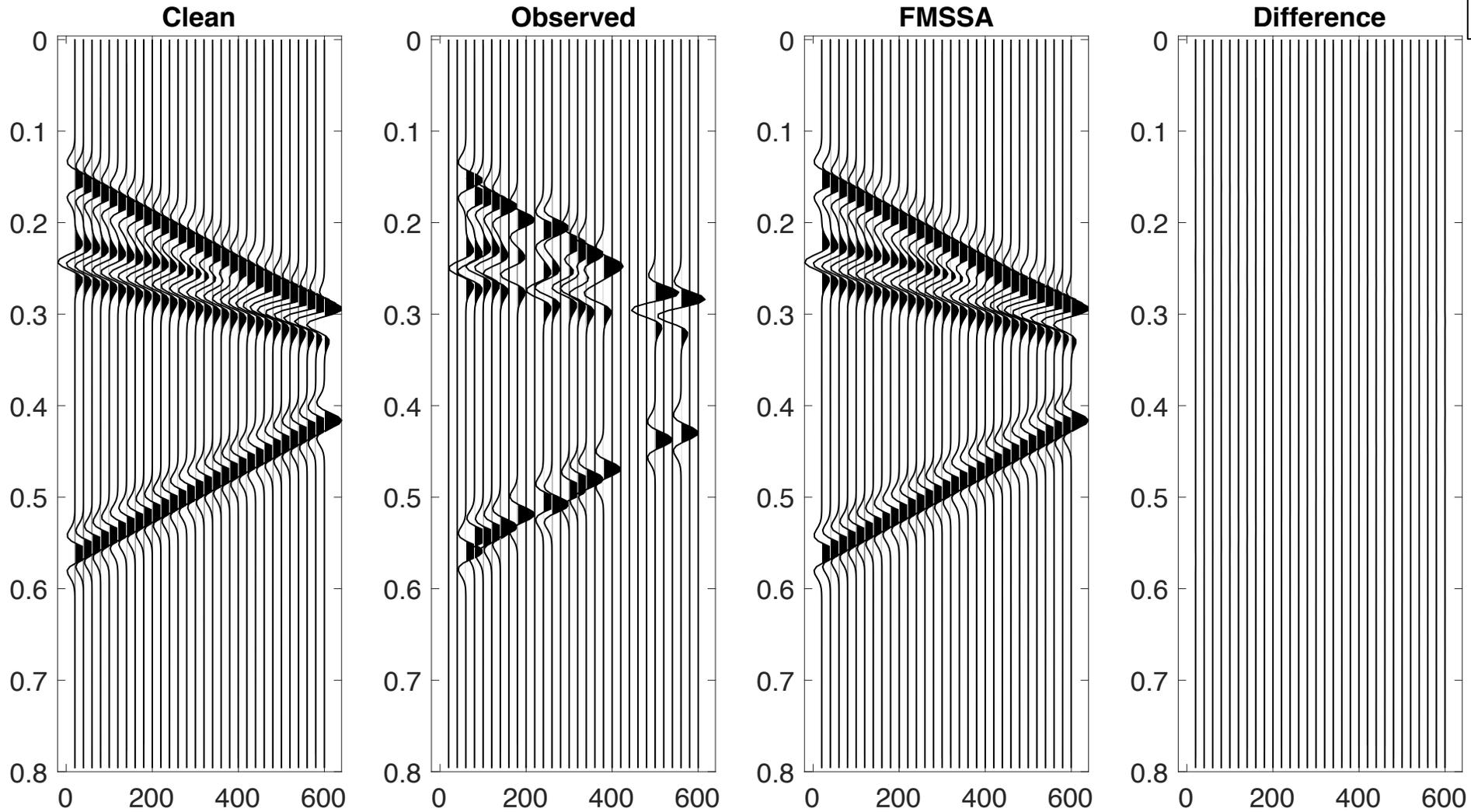
- I-MSSA*

Data size: 200x30x30  
Time = 31.92 s  
SNR = 45.9 dB



• *I-FMSSA*

Data size: 200x30x30  
Time = 7.71 s  
SNR = 46.7 dB

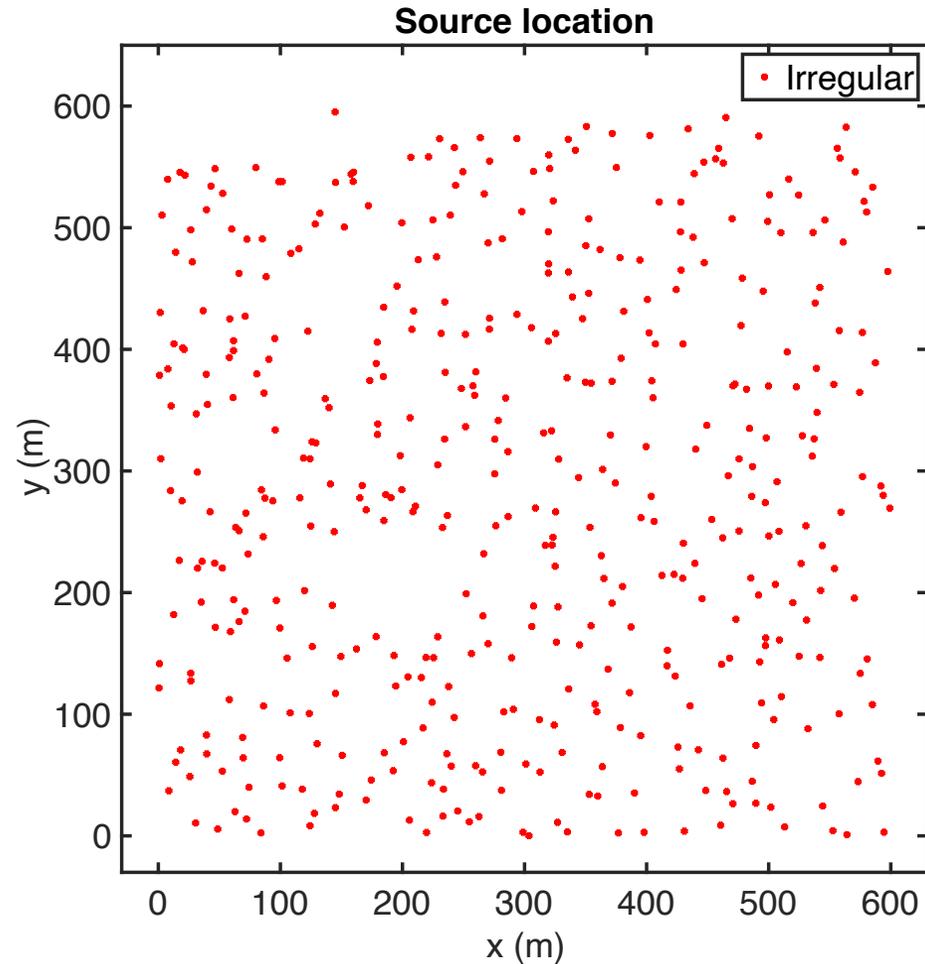


# Synthetic Example (EPOCS vs. I-FMSSA)

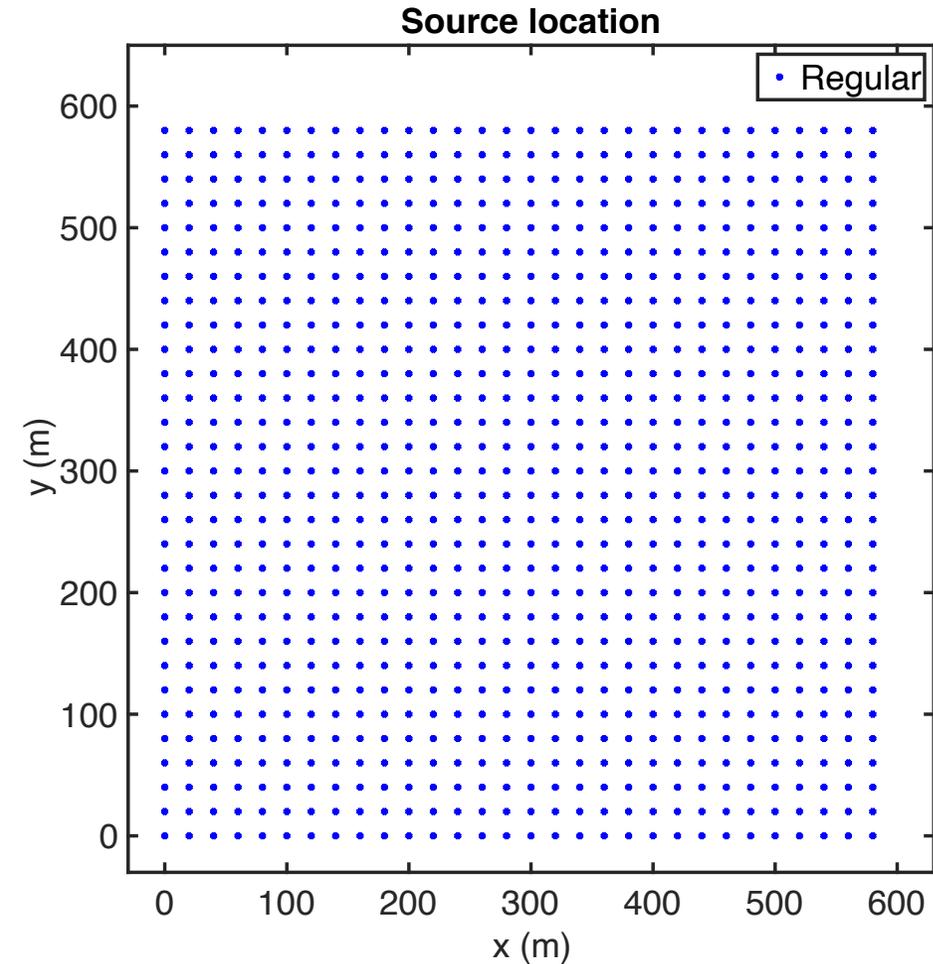
---



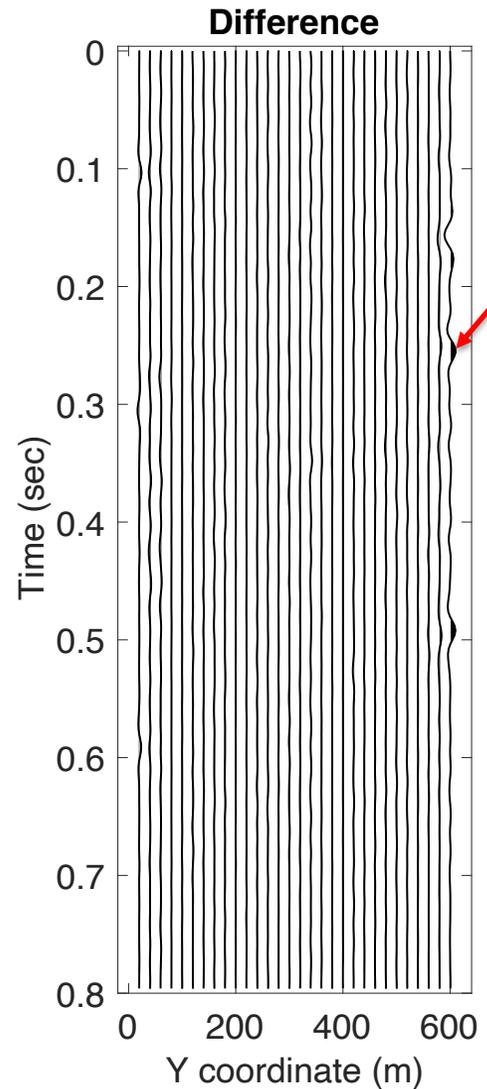
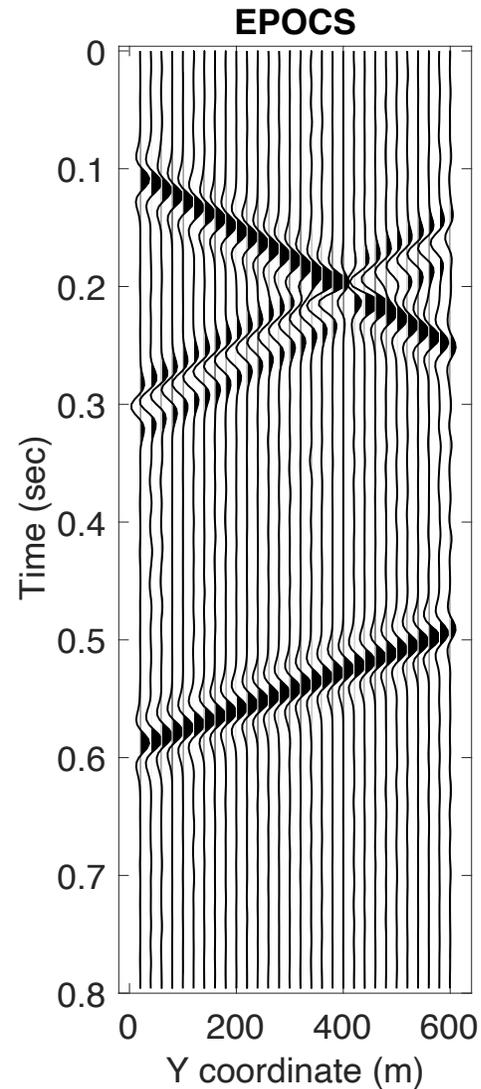
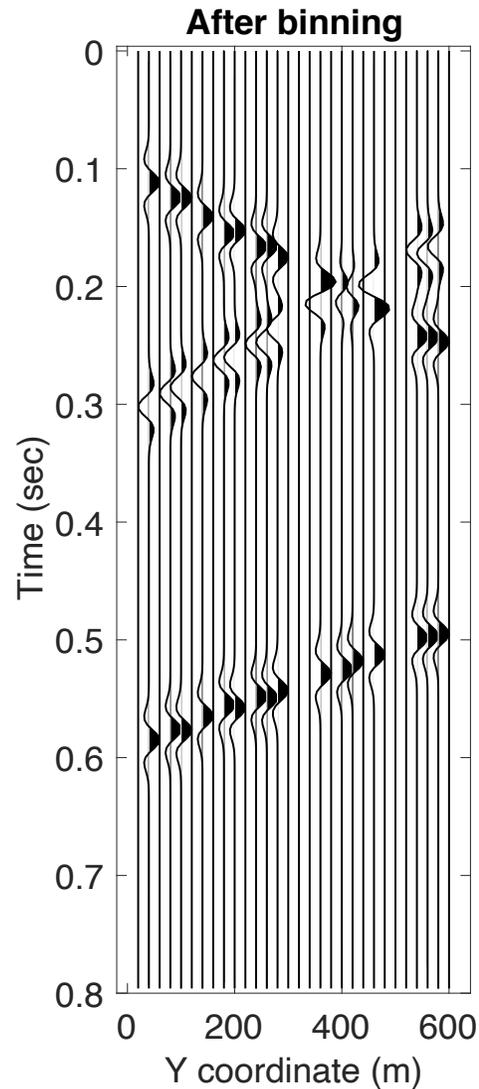
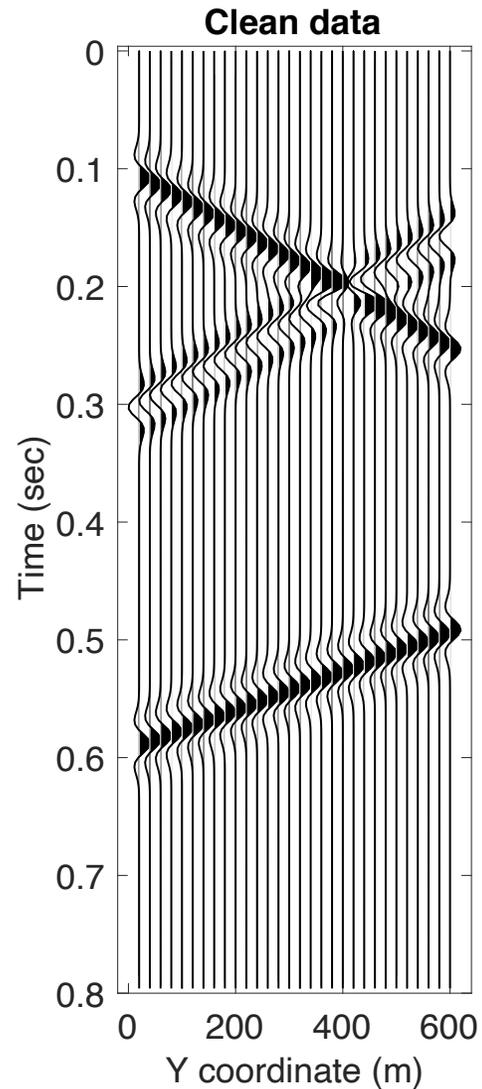
- Geometry of source location



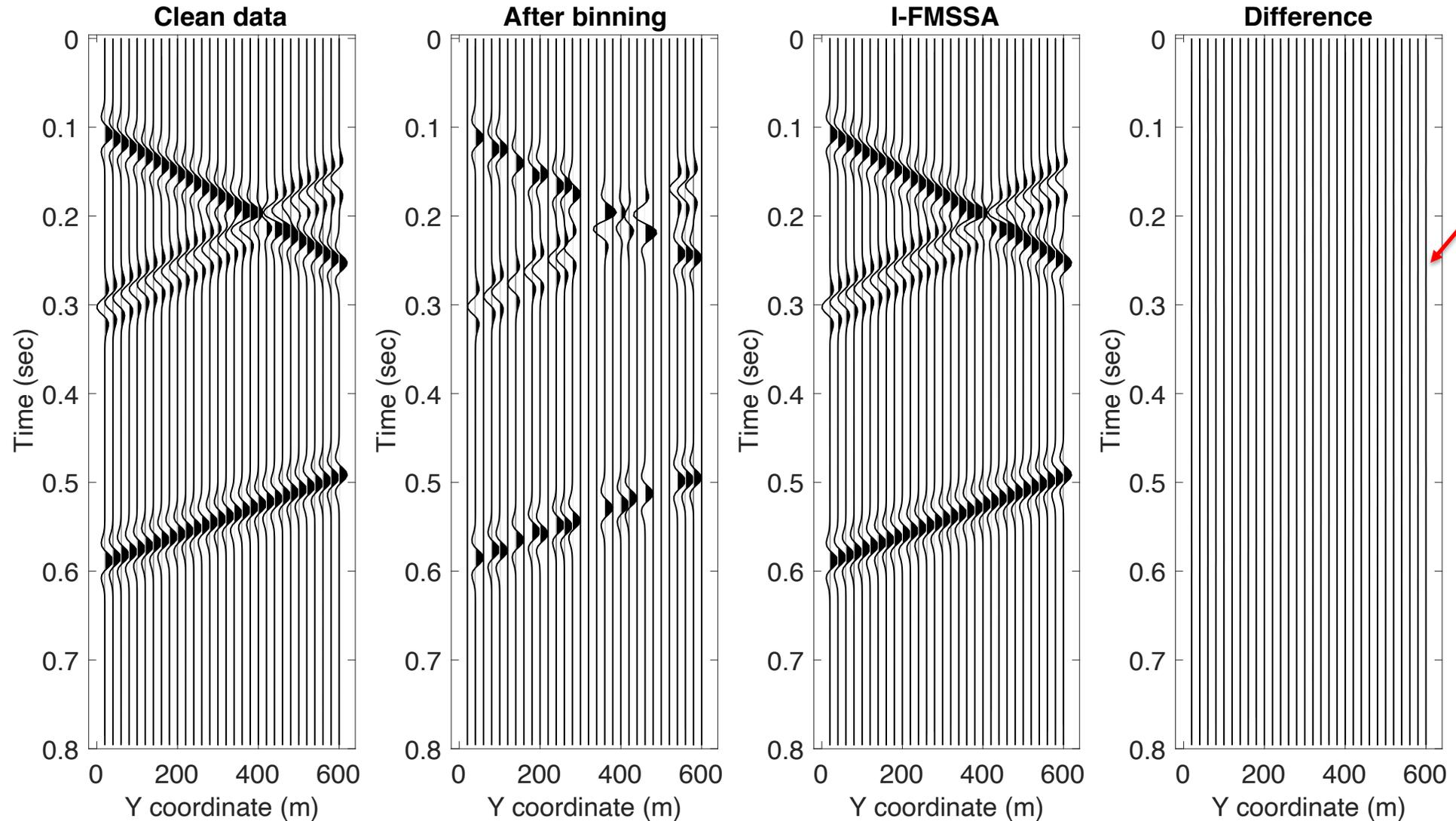
50% decimation



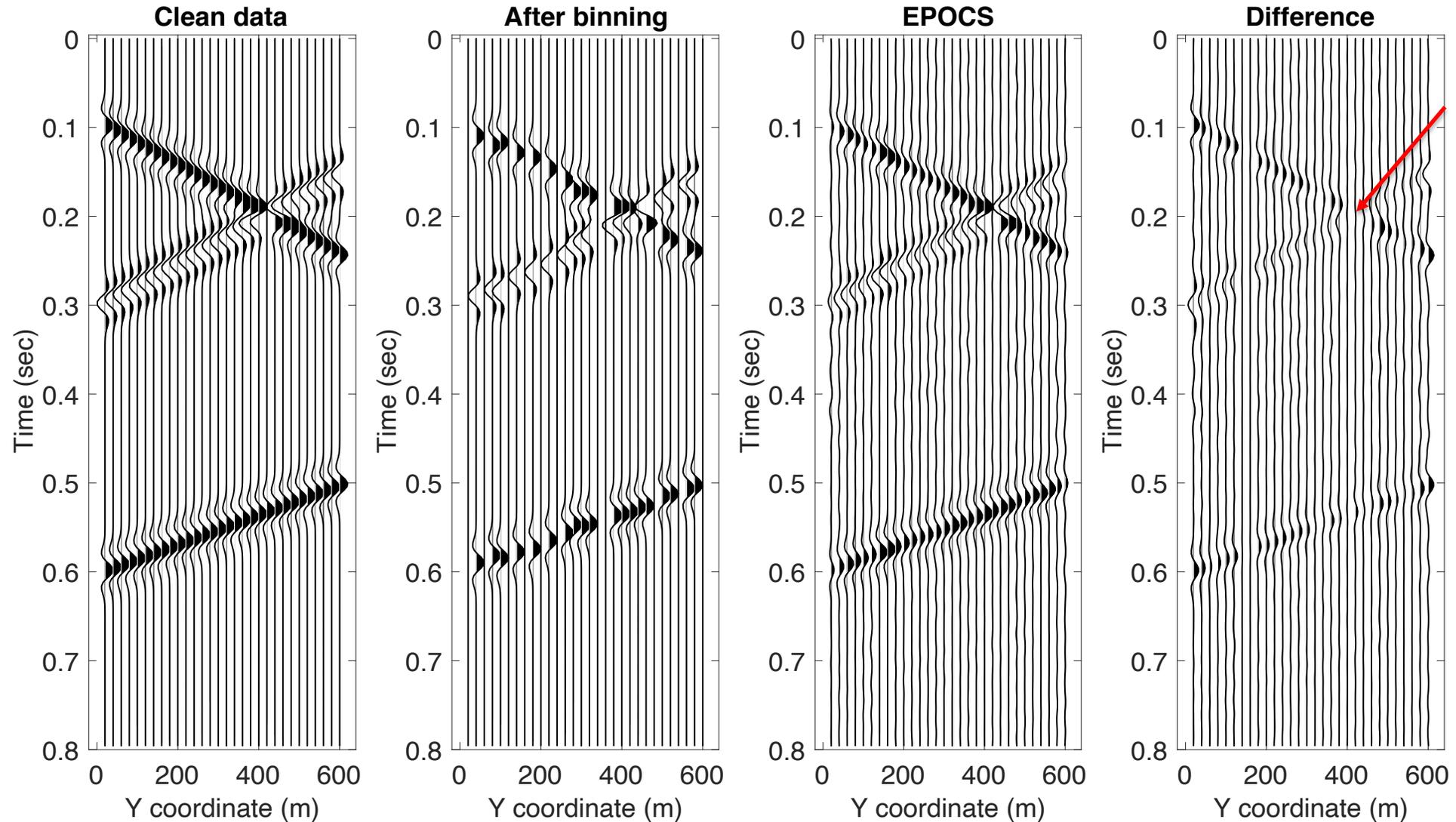
- EPOCS  $d(:,13,:)$



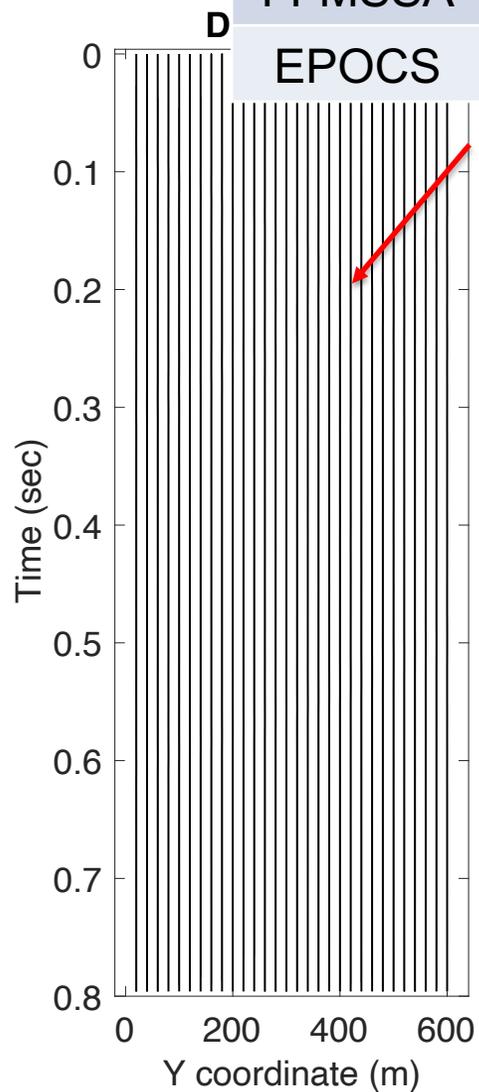
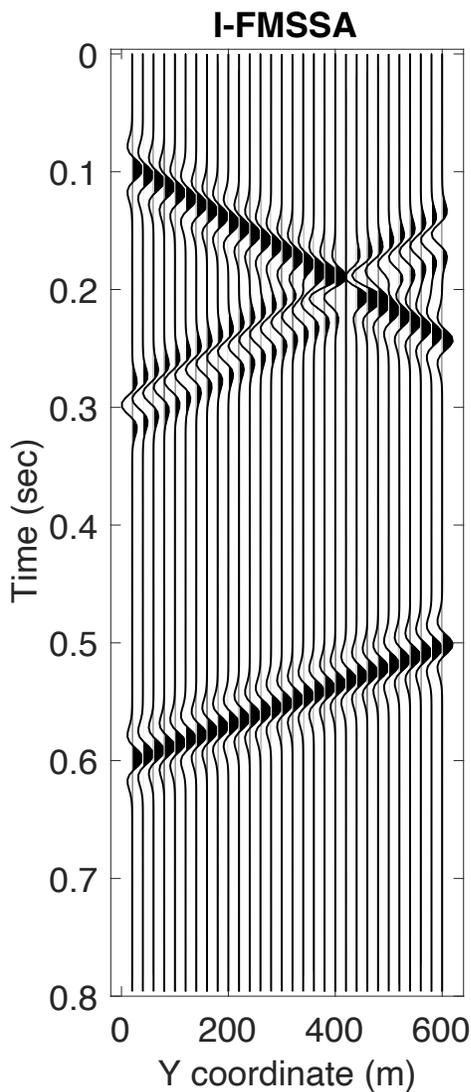
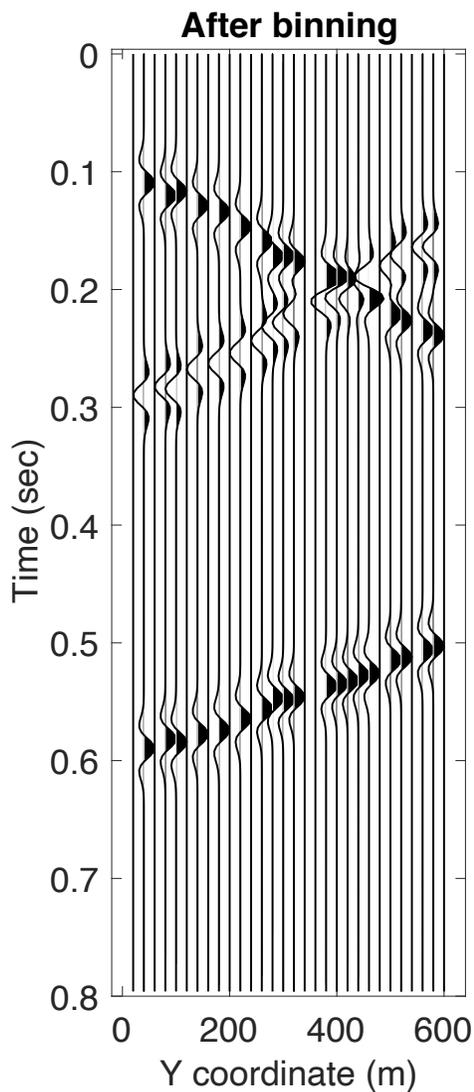
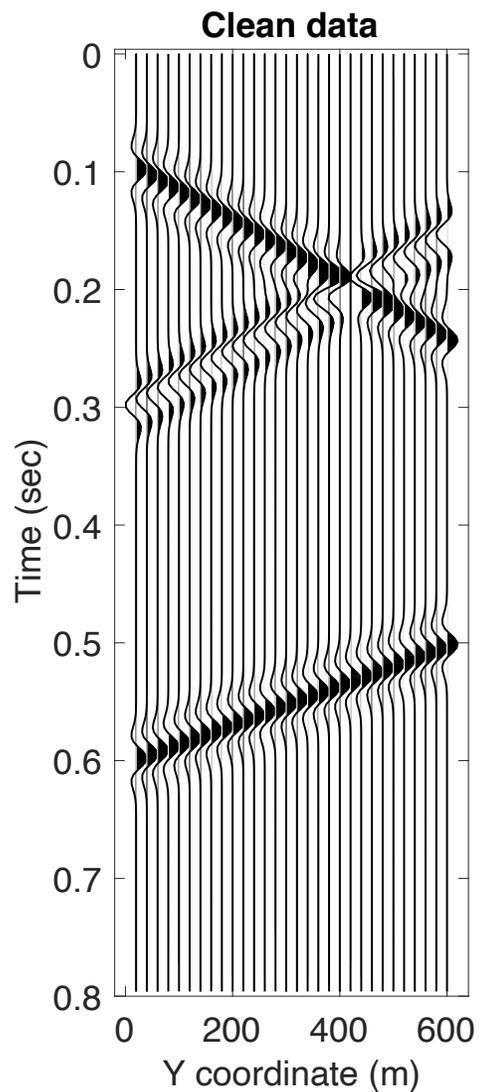
- I-FMSSA  $d(:,13,:)$



- EPOCS  $d(:,1,:)$



- I-FMSSA  $d(:,1,:)$



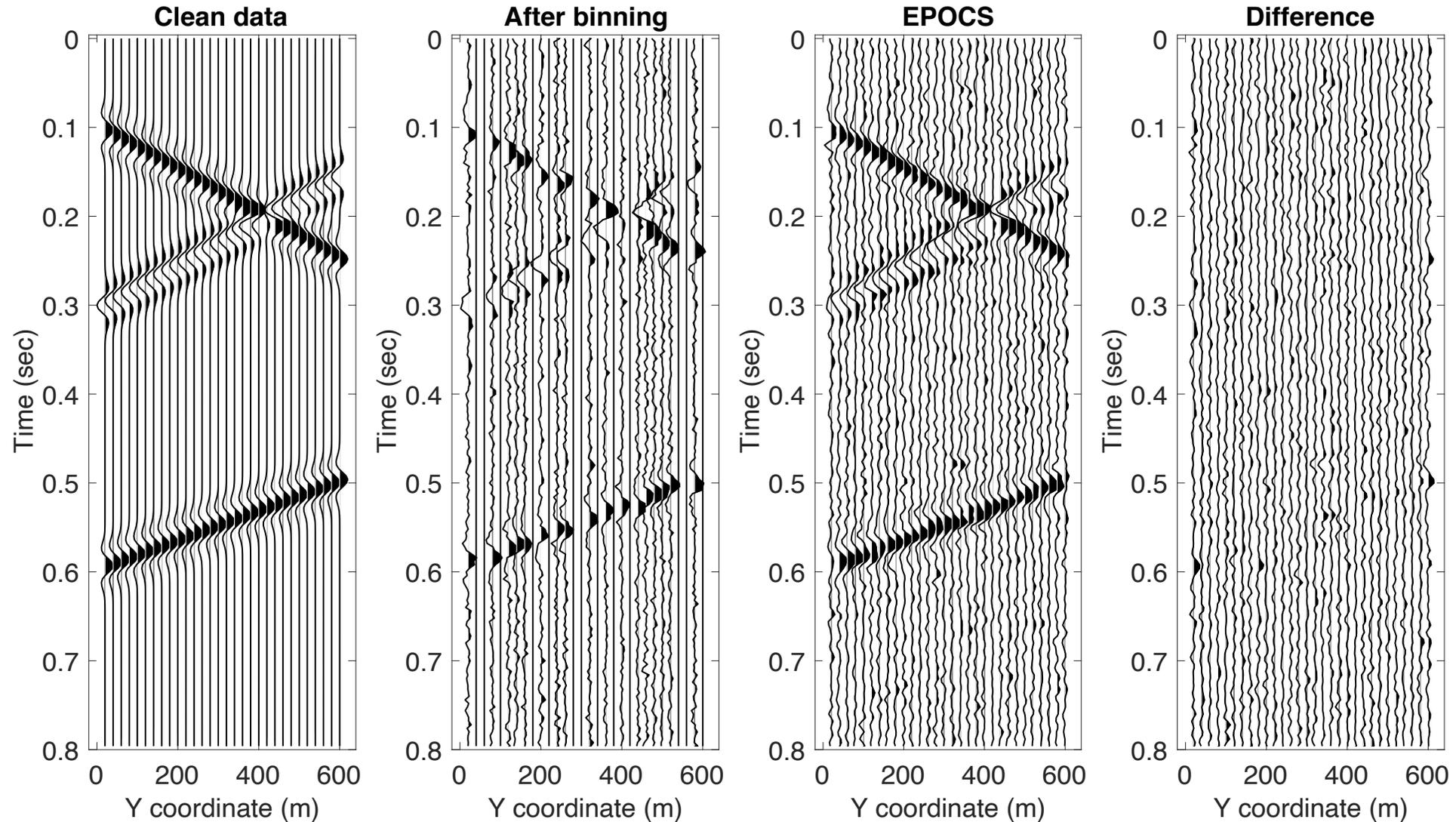
	SNR (dB)
I-FMSSA	47.30
EPOCS	16.18

## Synthetic Example (with random noise)

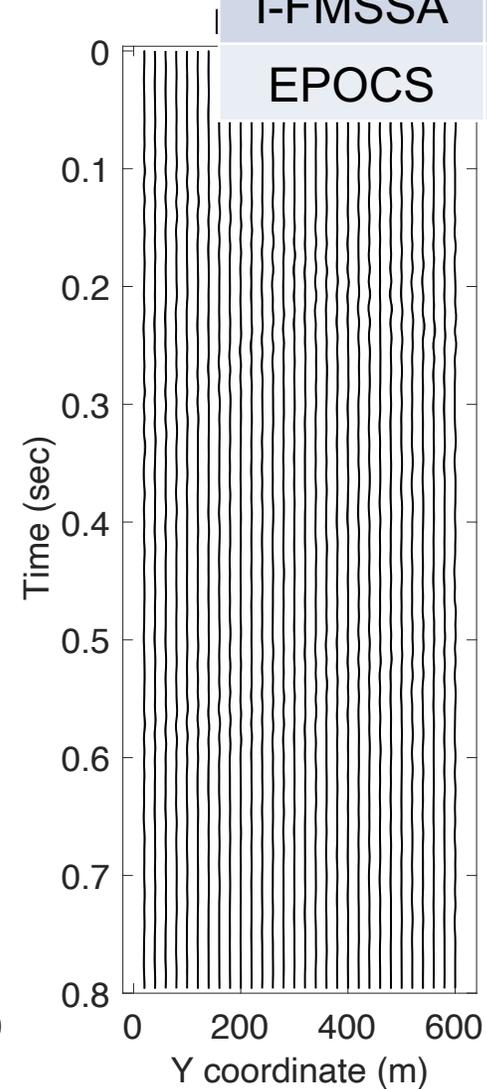
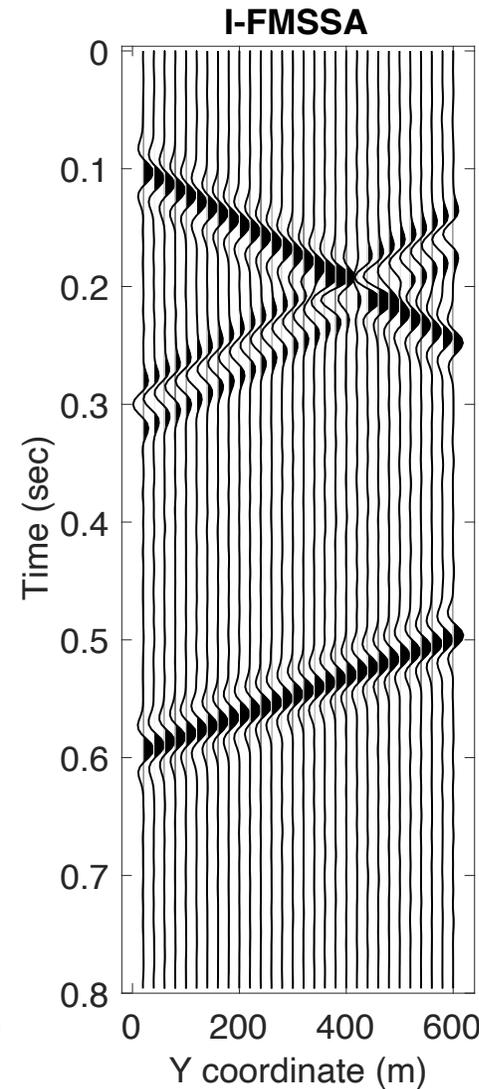
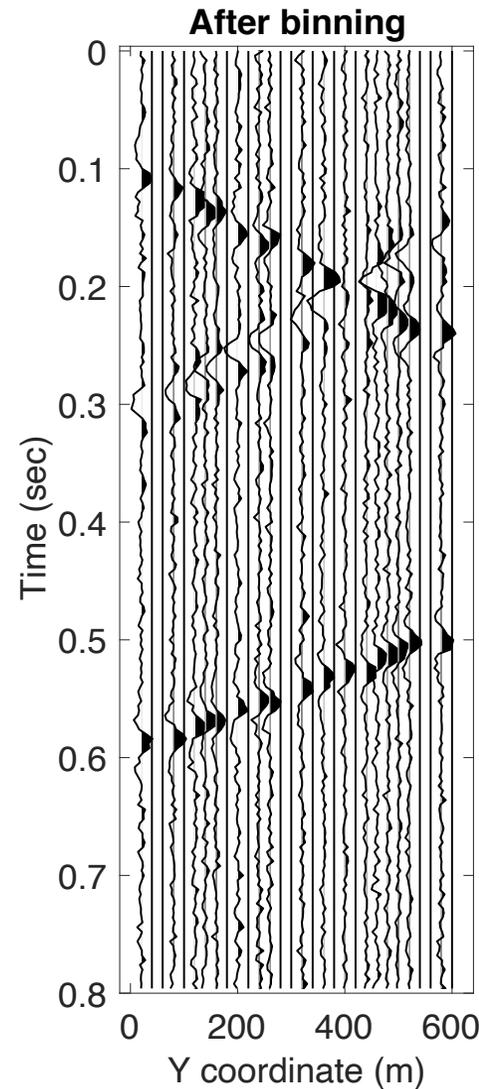
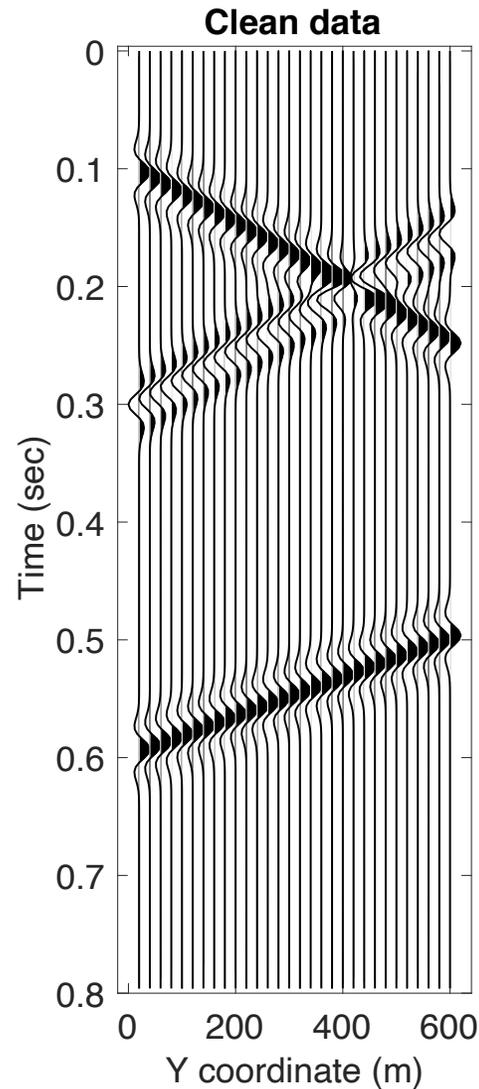
---



- EPOCS  $d(:,13,:)$



- I-FMSSA  $d(:,13,:)$



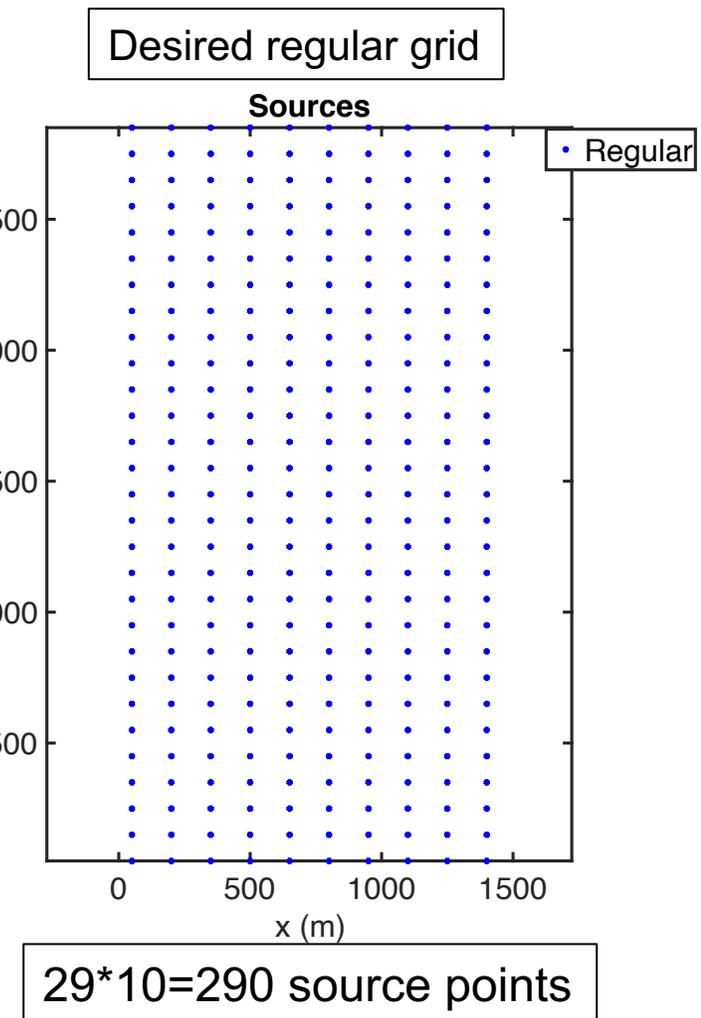
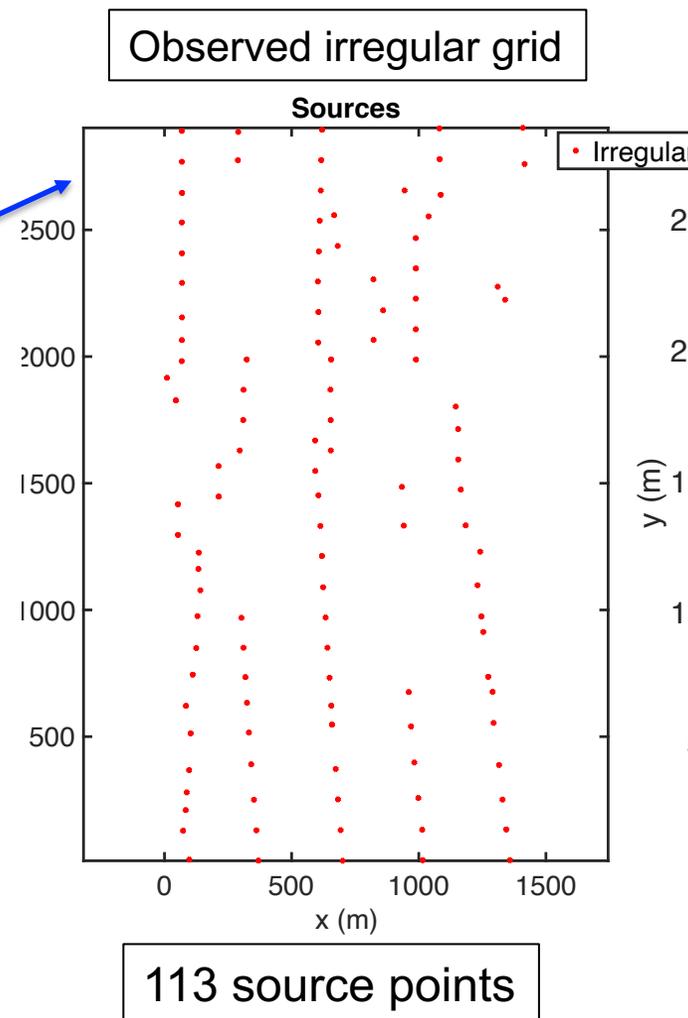
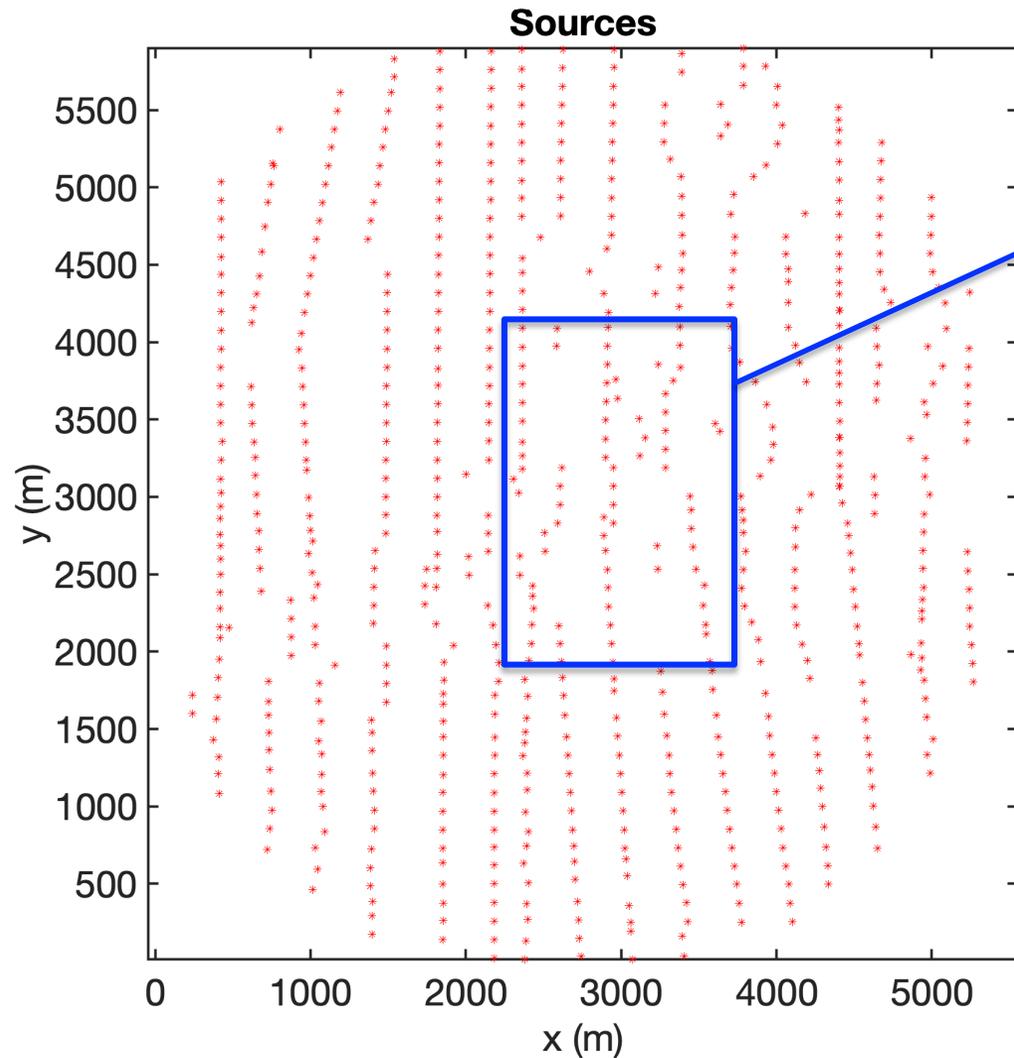
	SNR (dB)
I-FMSSA	20.74
EPOCS	3.44

# Real Example (Irregular Reconstruction)

---

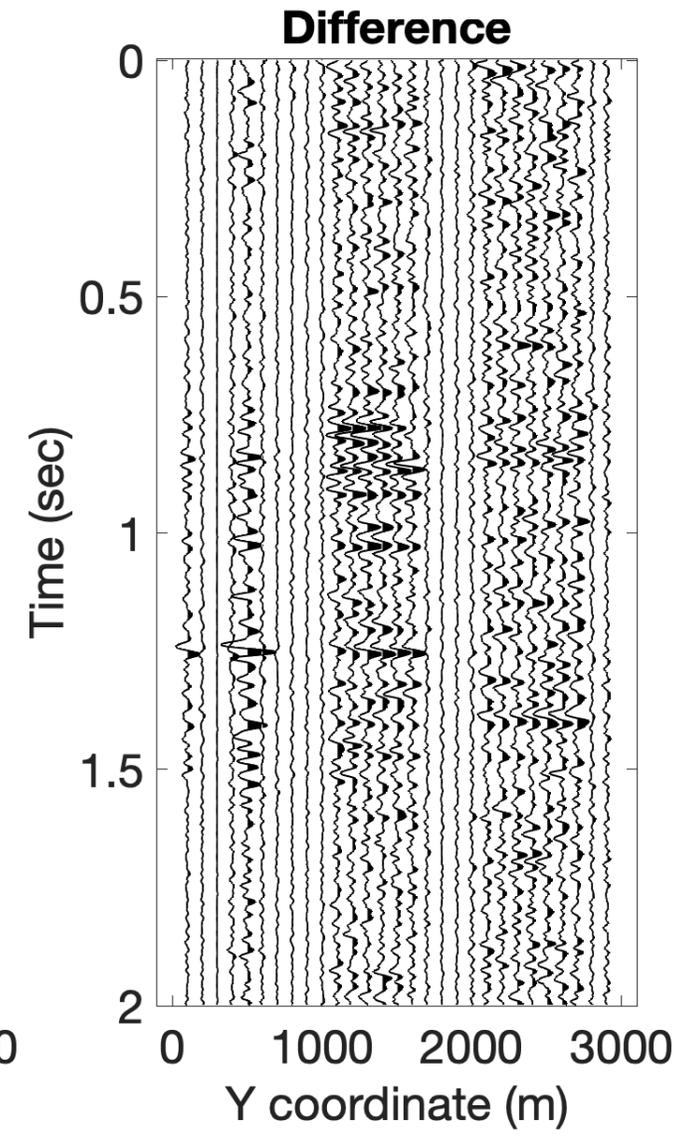
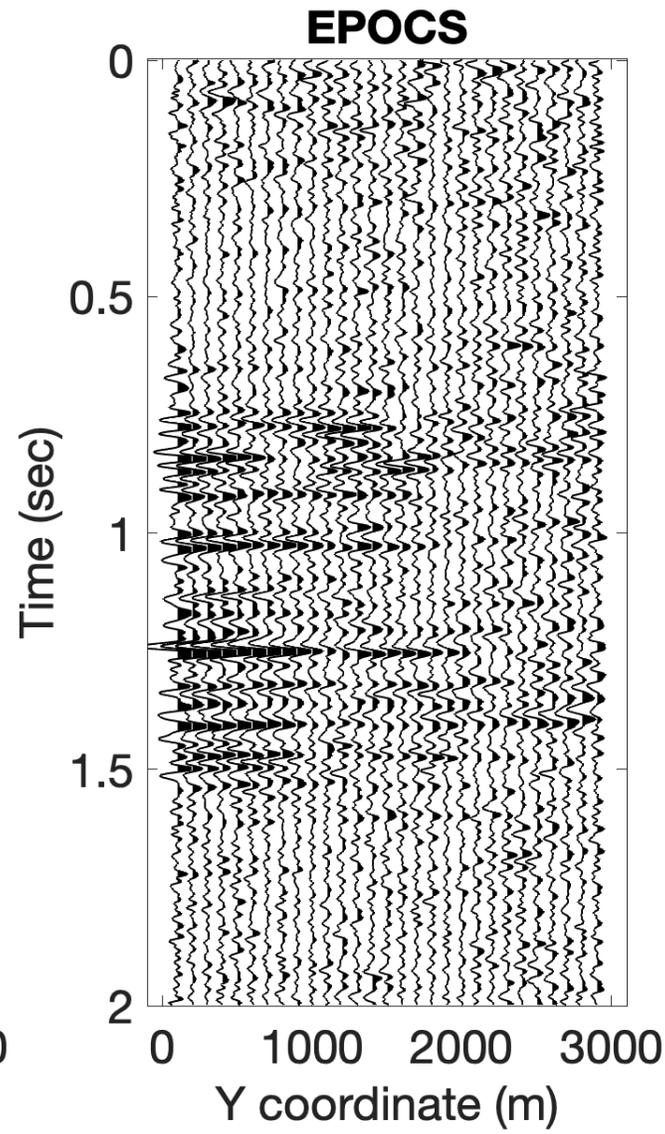
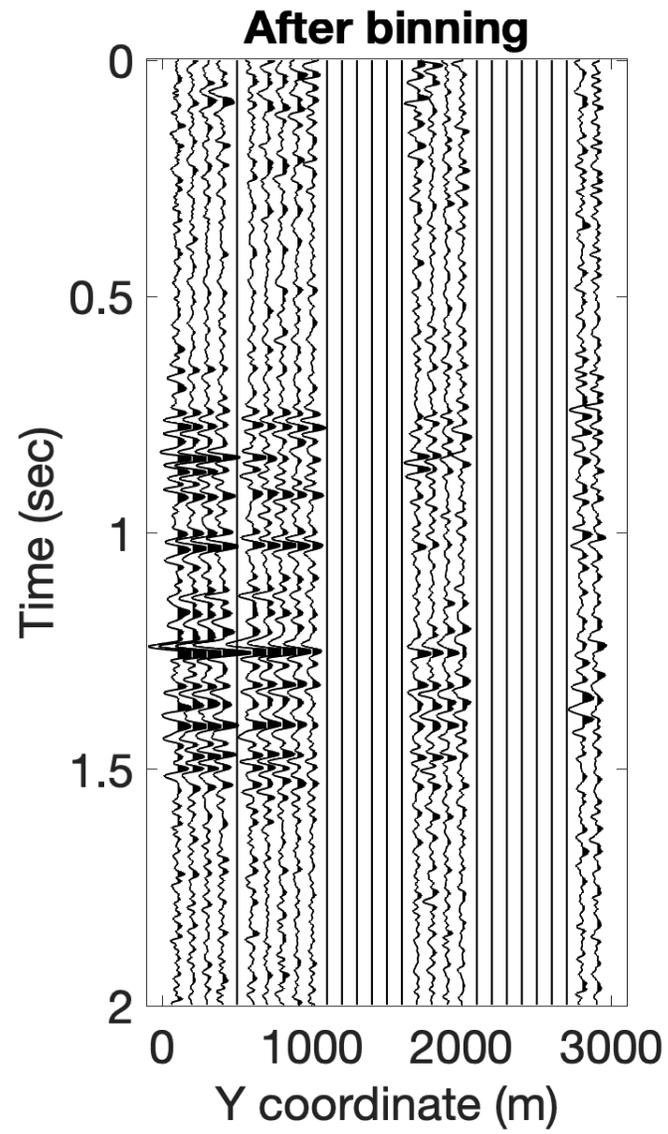


- Geometry of source location



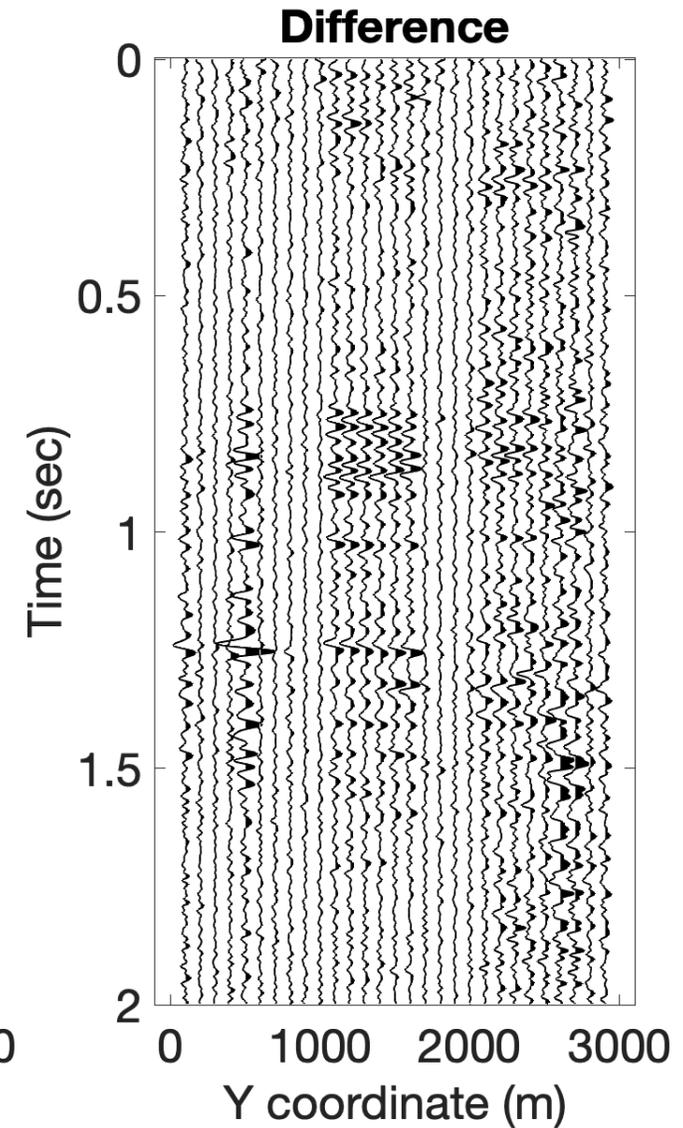
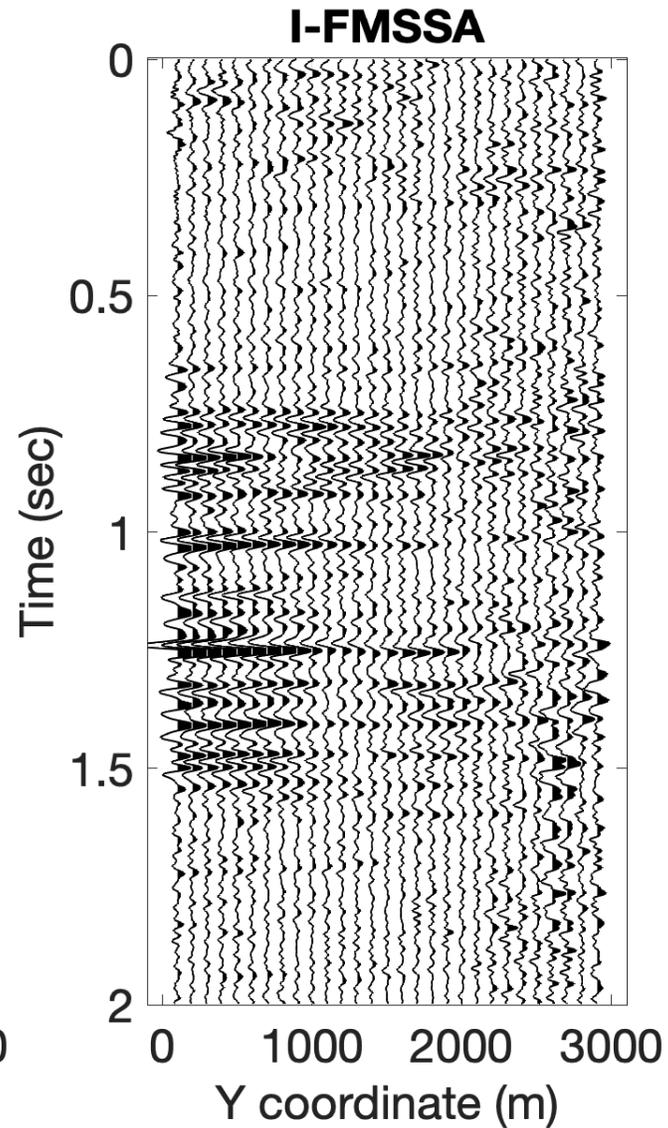
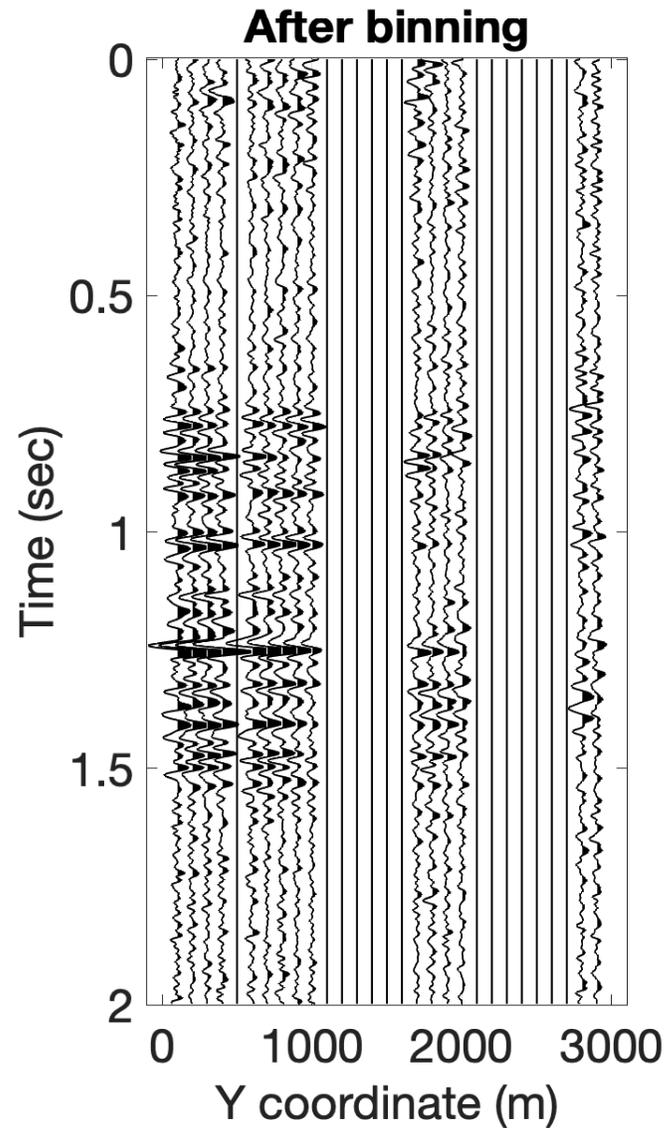
- EPOCS  $d(:,3,:)$

Inline slice



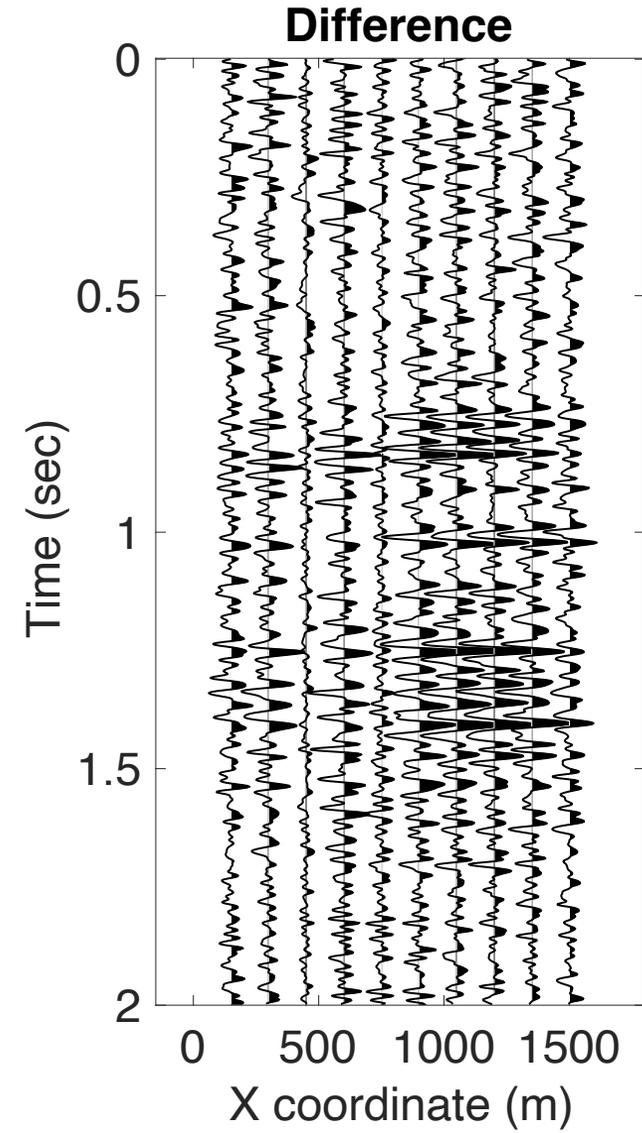
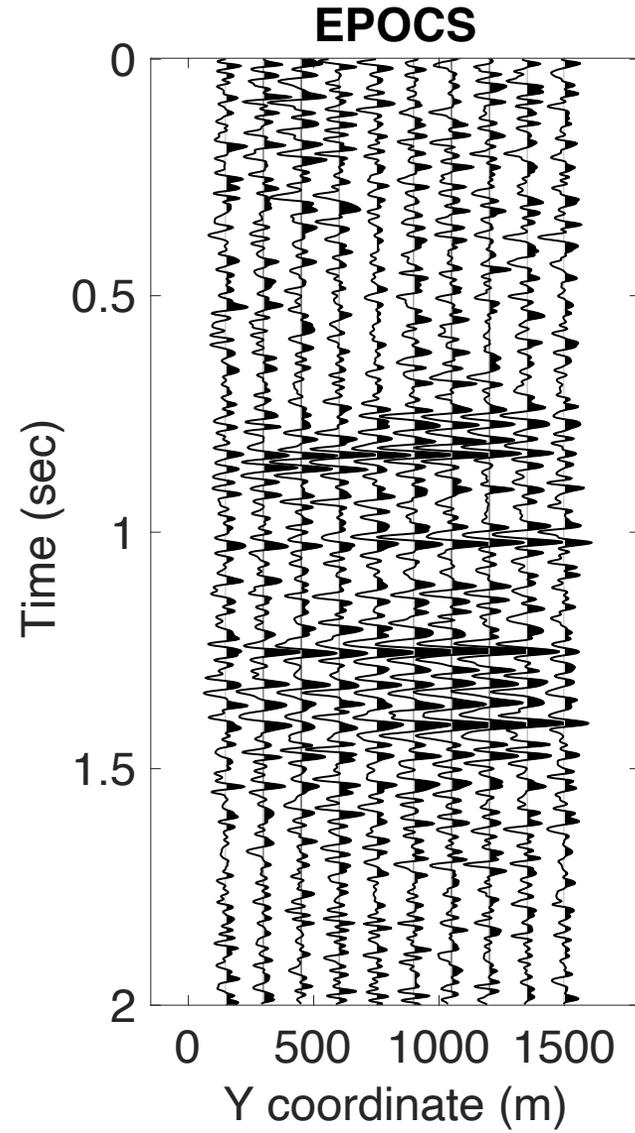
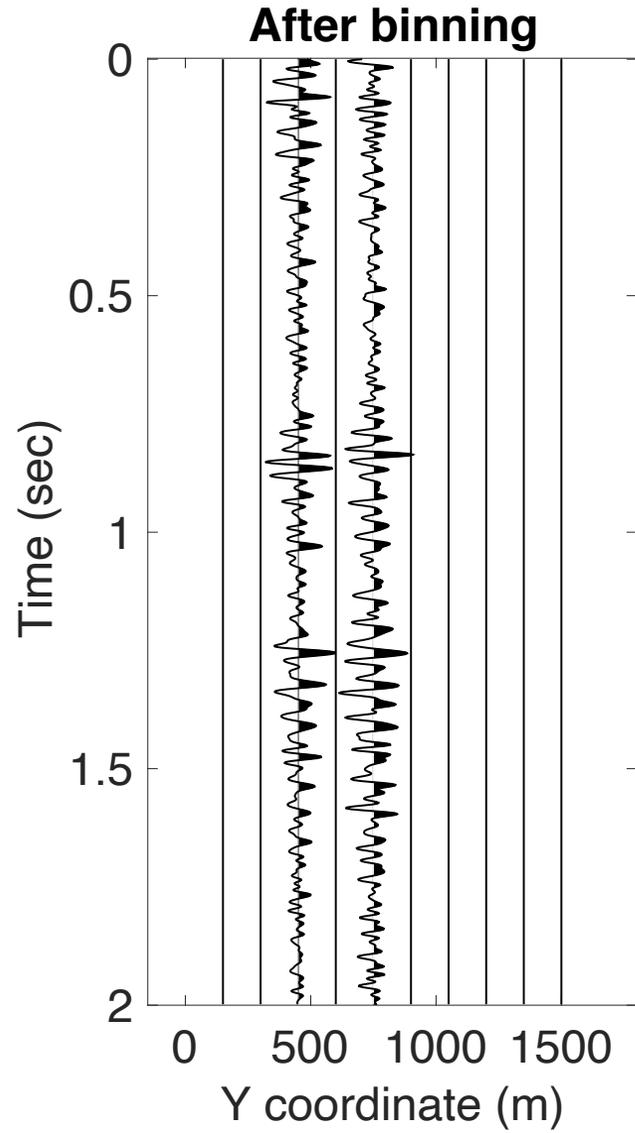
- I-FMSSA  $d(:,3,:)$

Inline slice



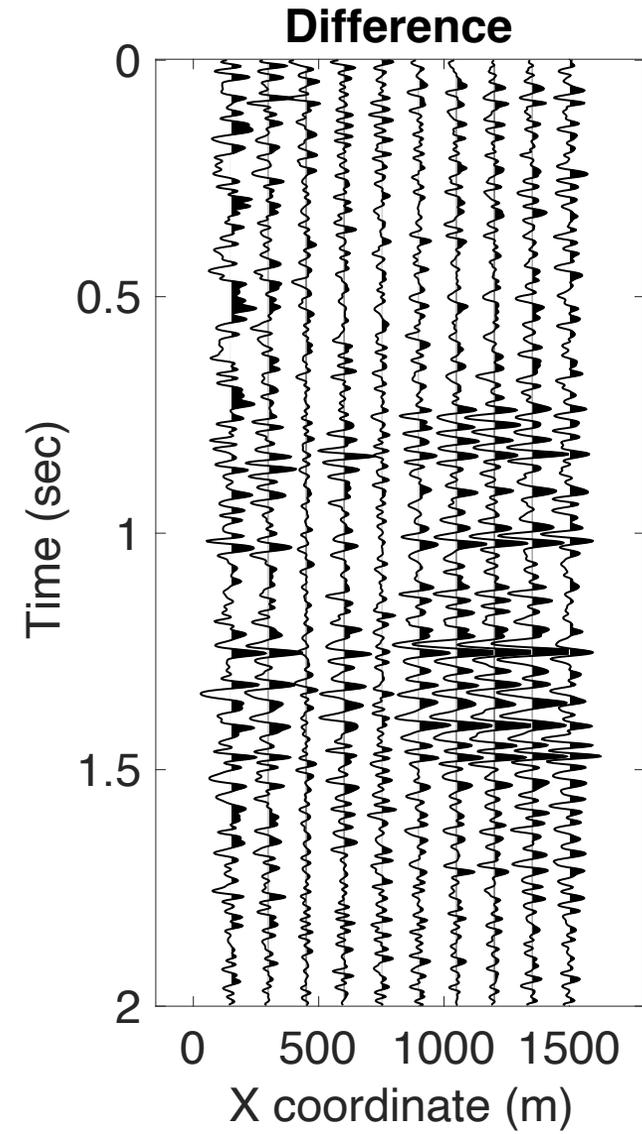
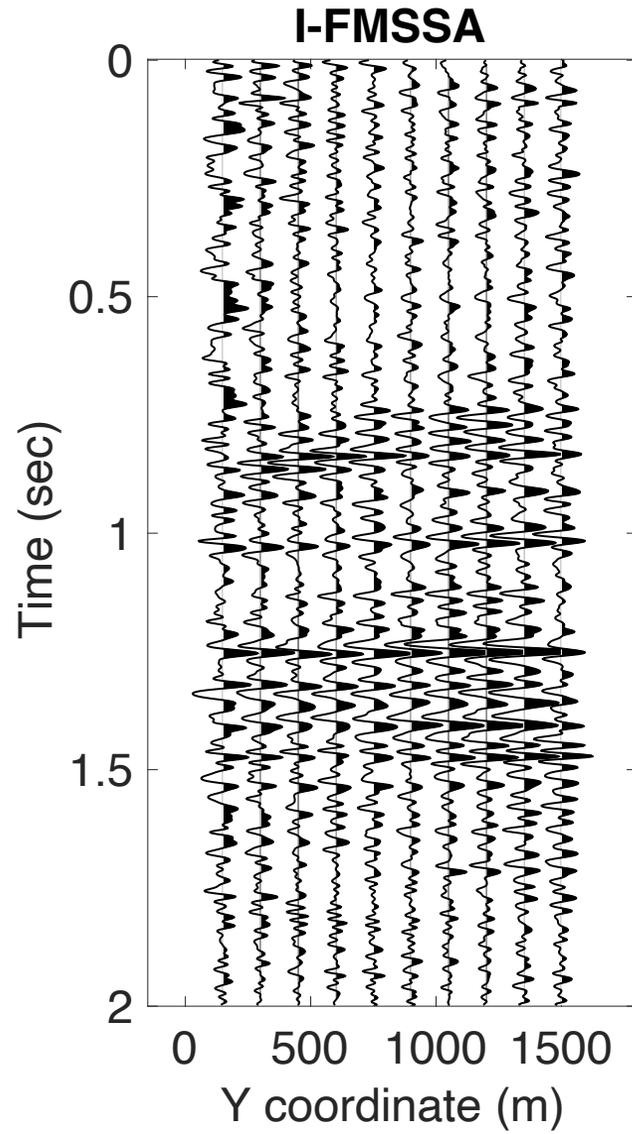
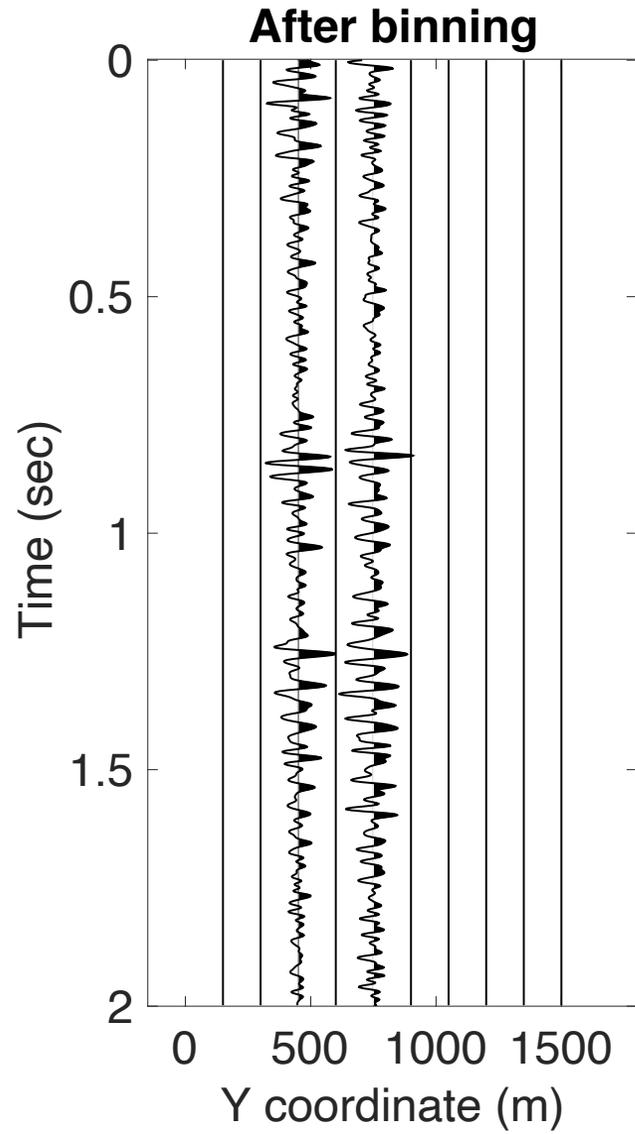
- EPOCS  $d(:, :, 17)$

Crossline slice



- I-FMSSA  $d(:, :, 17)$

Crossline slice



- Conventional SSA methods can be **expensive due to construction of Hankel structured matrices and singular value decomposition (SVD)**.
- The applied **fast and memory efficient SSA (FMSSA)** is an appropriate substitution for MSSA with reconstruction problems.
- EPOCS method will produce “**boundary effect**” for reconstruction and is not suitable for “**noisy**” data reconstruction.
- I-FMMSA method could be a good substitution for EPOCS with application for **irregular-grid data reconstruction**, and **simultaneous denoising and reconstruction**.

- *The sponsors of the Signal Analysis and Imaging Group (SAIG) at the University of Alberta.*